REVISED 7-17-87 Cable URIT DUG NO.\_ 2293287-503 SHUTTLE CCTY W 4.31.2 FMEA NO. ISSUED 10-14-86 CRITICAL TIEMS LIST SHEET CRITICALITY 2/1R FASLURE EFFECT FATEURE MODE AND RATIONALE FOR ACCEPTANCE ON END ITEM CAUSE No video or control DESIGN FEATURES ass of LOC 8 for locations requiring The H4 PTU cable is a 44-lack long, 25-wire assembly terminated by 37 pin connectors at each end. The video and symplomed wires are shielded Twinax shielded and twisted pairs hort to GND LDC 8. of #24 wire. The cable connects the TVC and PTU. Connector types KJG6E14N35SN16 have heen selected. Worst Case: No PTU contral of The cable design is taken from the successfully flown Apollo program. The design is a elbow camera to permit cable-connector assembly in which the wire terminations are protected from excessive arm stowage. flexture at the joint between the wire and the connector terminal. The load concentration is moved away from the conductor connection and distributed axially along the length of the conductors encapsulated in a potted-taper profile. This technique also protects the assembly from dirt and entrapped moisture which could cause problems in space. The cable and its components neet the applicable requirements of MASA, Military and RCA specifications. These requirements include: General/Mechanical/Electrical Features Design and Construction **Materials** Terminal Solderability **Environmental** Qualification Harking and Serialization Traceability and Documentation

REVISED 5-7-87 Cab le TINIT DMG NO. 2293287-503 SHUTTLE CCTV W 4.37.2 FMEA NO. TSSUED TO-14-85 CRITICAL ITEMS LIST SHEET CRITICALITY 2/18 FAILURE EFFECT FATCURE MODE AND RATIONALE FOR ACCEPTANCE. ON END ITEM CAUSE No video or control for QUALIFICATION TEST Loss of LOC 8 locations that do not Qualified by [.] similarity to previous successful space programs and 2.] by use during Short to GND regulare 100 8. qualification tests of CCTV LRUs. ACCEPTANCE TEST Morst Case: No PTU control of elbow The cable acceptance test consists of an chommeter check to assure that each wire connection is present and intact. Results are recorded on data sheets. camera to permit arm stowage. OPERATIONAL TEST The following tests verify that CCTV components are operable and that the commands from the PHS (AZAT) panel switch, through the RCU, through the sync lines to the Camera/PTU. to the Camera/PTU command decoder are proper. The tests also verify the camera's ability to produce video, the VSU's ability to route video and the conitor's ability to display video. A similar test verifies the MDM command path. Pre-Launch on Orbiter Test/In-Flight Test Power CCIV System. Select a monitor via the PHS pane), as destination and the camera under test as source. Send "Camera Power On" command from PHS panel. Select "External Sync" on monitor. Observe video displayed on monitor. If video on monitor is synchronized (i.e., stable raster), then this indicates that the camera is receiving composite sync from the RCU and that the camera is producing synchronized video. Send Pan, Tilt, Forus, Zoom, ALC, and Gamma commands and visually (either via the monitor or direct observation) verify proper operation. Select Bounlink as destination and camera under test as source. 7. Observe video routed to downlink. ø. Send "Camera Power Off" command via PHS panel. Repeat Steps 3 through 9 except issue commands via the MDM command path. This proves that the CCTV equipment is operational if video is satisfactory.

TAILURE MNDE AND  TO READ ITEM  No video or control for locations that do not require to C.S.  Morst Case:  No PIL Control of allow camera to permit arm sturvage.  No PIL Control of allow camera to permit arm sturvage and permit arm sturvage and permit arm sturvage.  No PIL Control of allow camera to permit arm sturvage and permit arm sturvage arm arm sturvage and permit arm sturvage arm arm sturvage arm arm arm sturvage arm arm arm arm arm arm sturvage arm			· · · · · · · · · · · · · · · · · · ·	REVISED 5-7-87
Inss of LOC 8  No video or control for locations that do not require LOC 8.  Nort to GNN  Horst Case: No PTU control of elbow camera to permit arm stumage.  No control of elbow comera to permit arm stumage.  No PTU control of elbow comera to permit arm stumage are made on all received materials and training split to permit arm stumage received by lot and retained in file by drawing materials and then several standard in the fabrication and test is possible of the retained in file by drawing and then several standard in lackuding assembly drawing notes and applicable documents called out in the fabrication are accumulated to form a kit. The items are verified out in the fabrication are accumulated to form a kit. The items are verified out in the fabrication are accumulate				155UE0 TO-14-86
Short to GNM    Directions that do not require 100 8.			NATIONALE FOR ACCEPTANCE	
ļ l	Loss of LOC 8	No video or control for locations that do not require LOC 8.  Horst Case: No PTU control of elbow camera to permit arm slow-	Procurement Control - Wire, connectors, solder, etc. and suppliers which meet the requirements set forth in Plan Work Statement (WS-2593176).  Incoming Inspection & Storage - Incoming Quality inspectant and parts. Results are recorded by lot and a control numbers for future reference and traceability. Material Controlled Stores and retained under specified fabrication is required. Non-conforming materials are (MRH) disposition. (PAI-307, PAI 196-53).  Assembly & Test - Prior to the start of assembly, all by stock room personnel as the items are accumulated to verified again by the operator who assembles the kit by as-built-parts-list (ABPL).  Specific instructions are given in assembly drawing not called out in the Fabrication Procedure and Record (FPI Process Standard crimping flight connector contacts, 20 splicing of standard interconnecting wire using Raycher Process Standard marking of parts or assemblies with equaterial and test procedure (TP-AT-2293287). Quality at the completion of key operations.  Preparation for Shipment - When fabrication and test-in packaged according to 2280746. Process Standard for Paid All related ducumentation Including assembly drawings, is yethered and held in a documentation folder assigned.	re procured from approved vendors the CCIV contract and Quality  ctions are made on all received retained in file by drawing and Accepted items are delivered to disconditions until cable held for Material Review Board Stems are verified to be correct or form a kit. The Items are yielded, against the testing against the testing against the testing against the poxy colors, 2280876. Potting and DCAS Inspections are performed as complete, the cable assembly is chaging and Handling Guidelines. Parts List, ABPL, Test Data, etc.

REVISED 5-7-87 TRIT Cable 2293287-503 10-14-85 SHUTTLE CCTV CRITICAL ITEMS LEST DWG NO. FMEA NO. H 4.31.2 ISSUED \_ SHEET 4 CHITICALITY \_\_2/18 TAYLURE MODE AND CAUSE FATEURE EFFECT AATIONALE FOR ACCEPTANCE ON END ITEM FALLURE HISTORY Luss of LOC 8 No video or control for There have been no reported failures during RCA testing, pre-flight or flight. locations that do not Short to GND require LOC 8. Worst Case: No PTU control of albow camera to permit arm stowage.

REVISED 5-7-87 Cable DNE NO. 2293287-503 SHUTTLE COTY FNEA NO. \_\_\_\_ W 4.31.2 CRITICAL ITEMS LIST ISSUED -10-14-B6 SHEET -CRELICALLTY 2/1R FATEURE MODE AND FATEURE EFFECT RATIONALE FOR ACCEPTANCE ON END ETEM CMISE OPERATIONAL EFFECTS Loss of LOC 8 No video or control for locations that do not Short to GND toss of ability to position the Elbon camera. Possible inability to stow the RMS if the require LOC 8. elbow camera physically interferes with a payload. If RMS cannot be stoned the port payload bay door cannot be closed. Loss of crew and vehicle. Worst Case: No PTU control of elbow CREW ACTIONS camera to permit arm stouage. Perform EVA to reposition the elbow camera, use AMS motion to reposition the camera, or jettison the RNS. CHEW TRAINING Crew should be trained in contingency EVA and RMS operations procedures. MISSION CONSTRAINT Do not manifest Elbow camera for any flight where the payload and the elbow camera can interfere with each other (for any pan or tilt angle). If the camera must be flown do not change the camera position until the interfering payload is deployed.